

Modeling Dynamic Functional Neuroimaging Data Using Structural Equation Modeling

Larry R. Price

Texas State University–San Marcos

Angela R. Laird and Peter T. Fox

*University of Texas Health Science Center at San Antonio
Research Imaging Center*

Roger J. Ingham

*Department of Speech and Hearing Sciences
University of California–Santa Barbara*

The aims of this study were to present a method for developing a path analytic network model using data acquired from positron emission tomography. Regions of interest within the human brain were identified through quantitative activation likelihood estimation meta-analysis. Using this information, a “true” or population path model was then developed using Bayesian structural equation modeling. To evaluate the impact of sample size on parameter estimation bias, proportion of parameter replication coverage, and statistical power, a 2 group (clinical/control) \times 6 (sample size: $N = 10$, $N = 15$, $N = 20$, $N = 25$, $N = 50$, $N = 100$) Markov chain Monte Carlo study was conducted. Results indicate that using a sample size of less than $N = 15$ per group will produce parameter estimates exhibiting bias greater than 5% and statistical power below .80.

Neuroscientists in the field of human functional brain mapping use imaging modalities such as positron emission tomography (PET), transcranial magnetic stimulation (TMS), and functional magnetic resonance imaging (fMRI) to indirectly detect neural activity simultaneously occurring in various regions across the entire brain through metabolic and blood-oxygenation measures. The neural activity occurring within these anatomical regions of interest (ROIs) and their associated causal pathways provide a framework for modeling the covariance structure within the collective system. During data acquisition, the brain is repeatedly imaged while

Correspondence should be addressed to Larry R. Price, College of Education, Professor/Associate Dean, Division of Educational Research, ED 2007, Texas State University–San Marcos, 601 University Drive, San Marcos, TX 78666. E-mail: lprice@txstate.edu

the individual is presented with stimuli or required to perform a task. Spatial variations in signal intensity across the acquired neuroimages reflect differences in brain activity during the presented stimuli or task performance. Statistical analysis of this functional neuroimaging data attempts to establish relationships between the location of activated brain regions and the particular aspect of cognition, perception, or other type of brain functioning being manipulated by the task or stimuli. Generally, this process proceeds by transformation of the data into matrix format with subsequent analyses conducted according to the general linear model (Friston, Holmes, et al., 1995; Holmes, Poline, & Friston, 1997).

Establishing these function–location relationships and uncovering areas of functional dissociation within the cortex has been a primary focus of research, but more investigators are progressing from simple identification of network nodes toward studying the interactions between brain regions. The aim is to understand how sets and subsets of networks function as a whole with the intent of accomplishing specific cognitive goals. Previous studies have analyzed both correlational and covariance structures between brain regions, and techniques for applying structural equation modeling (SEM) to neuroimaging data to investigate connections between brain regions have been under development since 1991 (McIntosh & Gonzales-Lima, 1991, 1994; McIntosh et al., 1994).

Initial application of SEM techniques to functional neuroimaging data was limited to a handful of researchers with advanced statistical backgrounds. In recent years, interest in SEM has increased due to improvements in and accessibility of commercial software and an unavoidable pressing need for the development of methods to test network models and investigate effective connectivity between neuroanatomical regions. Previous studies have applied SEM methods to PET and fMRI data as a means to investigate simple sensory and action processing, such as vision (McIntosh et al., 1994), audition (Gonçalves, Hall, Johnsrude, & Haggard, 2001), and motor execution (Zhuang, LaConte, Peltier, Zhang, & Hu, 2005), as well as higher order cognitive processing, such as working memory (Glabus et al., 2003; Honey et al., 2002), language (Bullmore et al., 2000), and attention (Kondo, Osaka, & Osaka, 2004), and multiple sclerosis (Au Duong et al., 2005). The analytic strategies that researchers conducting these studies have used either posited starting path models a priori based on a single theory alone and then proceeded in a confirmatory manner or an exclusively Bayesian approach to generate optimally weighted network models using little or no prior information. Two shortcomings of these previous studies are that the analytic strategies lack the ability to distinguish from multiple other equally plausible network models, and they did not consider the impact of sample size and its effect on statistical power and parameter estimation bias. To address these issues, we present a two-step approach that uses quantitative activation likelihood estimation (ALE) meta-analysis (Brown, Ingham, Ingham, Laird, & Fox, 2005; Turkeltaub, Guinevere, Jones, & Zeffiro, 2002) for identification of ROIs specific to our research problem in combination with Bayesian SEM to generate a highly informed network model. After model development, we examined issues that previous SEM-based neuroimaging studies have failed to address: sample size, statistical power, and parameter estimation bias. Given that the cost of data acquisition in functional imaging research is very high (e.g., approximately \$3,000 per participant), the question of the requisite sample size necessary to model the neural system in a statistically valid and reliable manner is crucial to the ongoing conduct of this work.

The overall aim of functional brain mapping is to determine where and how various cognitive and perceptual processes are controlled in the normal and abnormal (diseased) human brain.

In discussing the need for a comprehensive cognitive ontology, Price and Friston (2005) detailed a clear argument for the need for sophisticated network analysis tools. Because there are an immeasurably large number of thought processes that control cognition, perception, action, and interoception, and a finite number of brain regions involved in carrying out these processes, these regions must interact in a highly complex and organized fashion. Determining and characterizing these interactions is a natural and obvious application of SEM. There are advantages to applying SEM to data acquired in human functional brain mapping. For example, in contrast to other fields that utilize SEM methods, such as psychometrics, SEM of functional neuroimaging data involves the analysis of variables that represent actual cortical regions in the brain and path coefficients that reflect actual anatomical and functional connections between these regions. The connections between regions model the interregional covariances between physically remote brain regions. Because researchers know that these regions do not operate independently of each other, SEM or path analysis offers the distinctive ability to model the interrelationships of neural networks. An additional advantage of applying SEM methods to functional neuroimaging data lies in the characteristics of the data itself. Whereas raw neuroimaging image data can demonstrate significant nonnormal characteristics such as skewness and kurtosis, the derived imaging data used in SEM analyses are highly parametric and exhibit a high degree of measurement stability or reliability. This is due to extensive preprocessing procedures such as realignment, spatial normalization, and smoothing techniques (Ashburner & Friston, 1997; Friston, Ashburner, et al., 1995).

In this study, we present a two-step approach for developing a path analytic model using functional imaging data (i.e., PET data were acquired from normal participants or those exhibiting speech dysfunction while performing a reading task) representing regions of interest within the human brain. We then evaluated the impact of sample size on statistical power and parameter estimation bias on the model. The paradigm of speech production was chosen because it represents an extremely rich area of human brain mapping research and one in which the observed results are highly consistent, although highly distributed throughout the brain. Early PET research focused on determining the neural correlates of speech, a language attribute that is uniquely human and thus of great interest to the neuroscientific community (Bookheimer, Zeffiro, Blaxton, Gaillard, & Theodore, 1995; Petersen, Fox, Posner, Mintun, & Raichle, 1988; Price et al., 1994). Indeed, enough research has been published on the neural correlates of speech production to warrant not one but several quantitative meta-analyses of the overt reading paradigm (Brown et al., 2005; Fiez & Petersen, 1998; Fox et al., 2001; Turkeltaub et al., 2002).

The selection of suitable regions of interest and neural pathways in the human brain given the amount of information available to researchers is a challenging task. To meet this challenge, we used quantitative ALE meta-analysis (Brown et al., 2005; Turkeltaub et al., 2002) and Bayesian SEM to develop a “true” or population-based ROI model of speech production based on findings from previous studies. Next, to examine the issues of sample size, statistical power, and parameter estimation bias (i.e., robustness and accuracy), we conducted a Markov chain Monte Carlo (MCMC) simulation study. Additionally, we examined the sensitivity of the model to detect statistical differences in the structural regression weights and intercepts between clinical and normal participants across the sample size conditions. Although the underlying causal mechanisms of the neural correlates of speech in clinical and normal participants was not the focus of this study, we believe that the ability of the analytic strategy to detect statistical

differences in structural regression weights and intercepts between these groups provides a potentially powerful analytic tool to aid researchers in their work.

METHOD

Data Acquisition and Participants

The data for this study included PET images from a previous study examining the neural substrates of stuttering (Fox et al., 1996). Data included 10 male participants diagnosed with chronic developmental stuttering (M age = 32.2 years, age range = 21–46 years) and 10 male healthy control participants who were normally fluent (M age = 32.3 years, age range = 22–55 years). All participants gave informed consent according to the approved procedures of the Institutional Review Boards of the University of Texas Health Science Center at San Antonio and the University of California, Santa Barbara. All participants were scanned while they performed three tasks: eyes-closed rest (rest), unaccompanied overt paragraph reading of a text passage (solo), and overt paragraph reading while accompanied by a fluent audio recording of the same paragraph (chorus). Paragraphs for both the solo and chorus conditions were presented on a video display suspended above the participants, approximately 14 in. from the eyes. In the chorus condition, a recording of a nonstutterer reading the same passage was also presented via an earphone inserted into the left ear. Each 40-sec condition was imaged three times in all participants (each participant reading the same text passage on three separate trials); each participant underwent nine PET scans in a counterbalanced order.

PET imaging was performed with a General Electric (Milwaukee, WI) 4906 camera. Brain blood flow was measured with $H_2^{15}O$ (half-life 123 sec), administered intravenously. Reading commenced at the moment of tracer injection and was stopped after 40 sec of acquisition. Task-induced changes in neural activity were detected as changes in the regional tissue uptake of ^{15}O -water (Fox & Mintun, 1989; Fox, Mintun, Raichle, & Herscovitch, 1984). To optimize spatial normalization of the PET images, anatomical magnetic resonance imaging (MRI) data were acquired for each participants on a 1.9 Tesla Elscint Prestige (Haifa, Israel) using a high-resolution 3D Gradient Recalled Acquisitions in the Steady State (GRASS) sequence: repetition time (TR) = 33 msec, echo time (TE) = 12 msec, flip angle = 60° , voxel size = 1 mm^3 , matrix size = $256 \times 192 \times 192$, acquisition time = 15 min.

Image Preprocessing and Analysis

Each individual PET scan image was globally normalized by value-normalizing to whole brain mean activity and scaling to an arbitrary mean of 1,000 (Fox, Mintun, Reiman, & Raichle, 1988; Friston et al., 1990; Raichle, Martin, Herscovitch, Mintun, & Markham, 1983). The interscan and intrasubject movement was assessed and corrected in all PET images using the Woods algorithm (Woods, Mazziotta, & Cherry, 1992, 1993). PET and magnetic resonance images were spatially normalized relative to the Talairach and Tournoux (1988) standard brain template using the algorithm of Lancaster et al. (1995). Locations of brain activation were expressed as millimeter coordinates referenced to the anterior commissure as origin, the right, superior, and anterior directions being positive. Data were averaged across trials within each

TABLE 1
Region of Interest (ROI) Coordinates

<i>Brain Region</i>	<i>X</i>	<i>Y</i>	<i>Z</i>
Left primary motor cortex (LM1)	−46	−10	40
Right primary motor cortex (RM1)	54	−10	36
Left rolandic operculum (LRO)	−54	−8	20
Right rolandic operculum (RRO)	54	−8	20
Supplementary motor area (SMA)	4	−2	58
Cingulate cortex (CING)	−6	8	40
Left auditory cortex (LAUD)	−56	−14	4
Right auditory cortex (RAUD)	56	−26	2

Note. Networks nodes were selected from the image data obtained from healthy control participants. The center of mass of each ROI is presented here as a stereotactic coordinate in a standard brain template in Talairach space (Talairach & Tournoux, 1988). The ROIs extended 5 mm in each direction from the center of mass. Positron emission tomography counts of regional cerebral blood flow were averaged from the voxels in the ROIs from the rest, solo, and chorus conditions from each of the three repeated trials.

of the three conditions and within the two patient groups, and grand-mean images for solo and chorus conditions were compared to rest for stutterers and controls. Group mean subtraction images (solo–rest and chorus–rest) were converted to Z score images (statistical parametric images of Z scores).

Eight ROIs were extracted from this analysis based on ALE meta-analysis of previously conducted studies corresponding to areas of high brain activation during speech production: left and right primary motor cortex (LM1 and RM1), left and right rolandic operculum (LRO and RRO), left and right auditory cortex (LAUD and RAUD), supplementary motor area (SMA), and cingulate cortex (CING). The coordinates for these regions in Talairach space are presented in Table 1. In an ALE meta-analysis, groups of foci are pooled for convergence in location. This method was created by Turkeltaub et al. (2002), modified by Laird, McMillian, et al. (2005), and has been used with increasing frequency to provide insight on varying patterns of activation across studies in the human brain mapping literature (Fox et al., 2005; Grosbras et al., 2005; Laird, Fox, et al., 2005; McMillian, Laird, Witt, & Meyerand, 2007; Owen, McMillian, Laird, & Bullmore, 2005; Price & Friston, 2005).

Data Screening and Development of Region of Interest Variables

A total of 180 observations across 10 participants (3 trials or repeated measurements \times 3 imaging conditions \times 10 participants \times 2 groups: 1 clinical and 1 control) in 8 ROIs constituted the raw data matrix for both the clinical and control groups. In both groups, there were no missing data points in the matrices and the assumption of univariate and multivariate normality was found to be tenable according to univariate z statistics (± 1.96) and Mardia's (1970) multivariate criteria.

Prior to deriving the composite ROI variables, we examined the data according to the following psychometric and statistical criteria: (a) autoregressive properties of the three trials or repeated measurements for each ROI averaged across scan condition, (b) the interaction effect between scan condition and trial within each ROI, and (c) the measurement and structural properties of each ROI by specifying eight separate correlated-error measurement models. First we examined the autoregressive properties of the three repeated measurements for each ROI by fitting general Markov and stationary Markov (lag-2 and lag-3 time effects) models as a function of each successive measurement within each respective ROI, plus a random error component (Arbuckle, 1996; Wothke, 2000). Because the general Markov and stationary Markov models are hierarchically nested, chi-square difference tests were conducted for each ROI to determine the existence of a lag-2 or lag-3 time effect. In all eight ROIs, the stationary Markov model was rejected, indicating the presence of a lag-1 time effect across the successive measurements. Based on the results of these tests, aggregated composite variables were created (Bagozzi & Edwards, 1998) using the three correlated measurements obtained for each ROI using a weighting scheme that incorporated the lag-1 time effect.

Second, to examine the interaction between scan condition and trial within each ROI, eight univariate analyses of variance were conducted. No statistical interaction between scan condition and trial was observed for either the clinical or control groups.

Finally, we examined the measurement and structural properties for each ROI by regressing each region on the three repeated measurements (averaging over scan conditions) for a particular region. For the eight regions of interest, each measurement model exhibited excellent fit to the data. In each ROI, we screened the data based on the recommendation of Hoyle and Kenny (1999), that prior to deriving the ROI composite variables, the reliability coefficients of each of the ROI composites should be equal to or greater than .90. Hoyle and Kenny (1999, p. 202) noted that this screening step is particularly critical in composite variable path analytic models that include mediator variables and sample sizes of less than 100 to minimize the impact of measurement error on parameter estimates and statistical power.

After screening and evaluating the requisite assumptions for using an aggregated composite variable path analytic approach, our derivation of the ROI variables proceeded by adhering to the conventions presented in McDonald (1996). McDonald's criteria for using composite variables within the SEM framework are (a) the variables are "random" (e.g., in this study the data captured using PET scans were obtained from participants in a true experimental setting), (b) a random composite variable is a function (e.g., an optimally weighted sum in this case) of component random variables if and only if each of its components is observable, and (c) each of the ROI composite variables is represented as a "block." An observed (composite) variable approach, rather than a latent variable approach, was used in this study for the following reasons. First, we were limited to three measurements on each ROI for only 10 participants in each study group. Second, because the ROIs of interest are existing anatomical structures within the human brain, an observed variable approach is logical and provided a parsimonious approach to our model development. Third, the process for investigating and modeling the correlated structure of the three repeated measurements on each participant was more parsimonious. Finally, the reliability of each ROI composite variable was greater than .90, thereby making any gains by correcting for attenuation of measurement error using a latent variable approach negligible.

Population Model Development Using Bayesian SEM

The history and development of Bayesian statistical methods are substantial and closely related to frequentist statistical methods. In fact, Gill (2002) noted that the fundamentals of Bayesian statistics are older than the current dominant paradigms. In some ways, Bayesian statistical thinking can be viewed as an extension of the traditional (i.e., frequentist) approach, in that it formalizes aspects of the statistical analysis that are left to uninformed judgment by researchers in classical statistical analyses. In the Bayesian modeling approach, researchers view any unknown quantity (e.g., parameter) as random and these quantities are assigned a probability distribution (e.g., normal, Poisson, multinomial, geometric, etc.) that provides the impetus for generating a particular set of data at hand. In this study, our unknown population parameters were modeled as being random and then assigned to a joint probability distribution. In this way, we were able to summarize our current state of knowledge regarding the model parameters. At present, the sampling-based approach to Bayesian estimation provides a solution for the random parameter vector θ by estimating the posterior density or distribution of a parameter. This posterior distribution is defined as the product of the likelihood function (accumulated over all possible values of θ) and the prior density of θ (Lee & Song, 2004). The process of Bayesian statistical estimation approximates the posterior density or distribution of say, y , $p(\theta|y) \propto p(\theta)L(\theta|y)$ where $p(\theta)$ is the prior distribution of θ , and $p(\theta|y)$ is the posterior density of θ given y . This expression exemplifies the principle that updated knowledge results from combining prior knowledge with the actual data at hand. Finally, Bayesian sampling methods do not rely on asymptotic distributional theory and therefore are ideally suited for investigations in which small sample sizes are common (Ansari & Jedidi, 2000; Dunson, 2000; Scheines, Hoijtink, & Boomsma, 1999).

Development of our ROI population model proceeded by specifying the scheme of relations among the ROIs within the brain, as presented in Figure 1. The ROIs used in Figure 1 were selected based on the results of ALE meta-analysis of previous studies investigating the neural

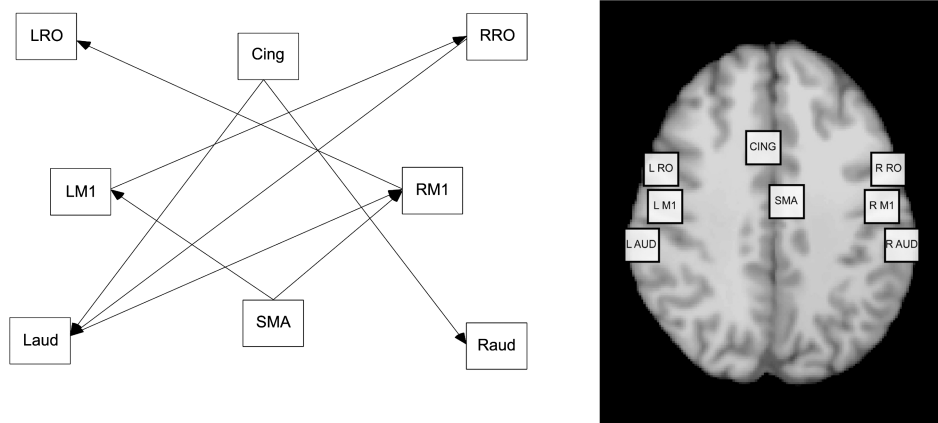


FIGURE 1 Region of interest path model.

correlates of speech. The direction and scheme of the paths illustrated in Figure 1 were posited based on a theoretically plausible neural activation network scheme derived from ALE meta-analysis and then verified by conducting a Bayesian SEM specification search algorithm.

The model in Figure 1 served as the baseline for Bayesian estimation of the model parameters using the MCMC methodology (i.e., Metropolis–Hastings algorithm) and Gibbs sampling (Geman & Geman, 1984). The estimation process proceeded by using centered parameterization, allowing the composite ROI variables to have free intercepts and variances and diffuse (noninformative) uniform priors for the vector of parameters, including the variance components. Although the conceptual design of our path model (i.e., ROIs and regression paths) was informed by ALE meta-analysis, we used a noninformative normal prior distribution for structural regression weights and variance components to prevent the possible introduction of parameter estimation bias due to potential for poorly selected priors (Jackman, 2000; Lee, 2007, p. 281). We followed guidelines offered by Raftery and Lewis (1992) in determining the selection of the number of MCMC burn-in iterations with respect to establishing the convergence criteria for the joint posterior distribution of the model parameters. Based on a review of convergence diagnostics, we selected a burn-in sample of $N = 1,000$ and the convergence criterion for acceptable posterior distribution summary estimates of parameters was set at 1.001. Additionally, we examined the posterior distribution by evaluating time series and autocorrelation plots to judge the behavior of the MCMC convergence. In both instances, the plots revealed no abnormalities regarding the performance of the MCMC method. Bayesian estimation (incorporating the MCMC algorithm) of the model parameters was conducted using the Bayesian SEM facility in the Analysis of Moment Structures 6.0 (AMOS; Arbuckle, 2005) computer program. Table 2 provides the means, standard deviations, and lower and upper 95%

TABLE 2
Posterior Summary of Bayesian Estimates ($N = 100,000$ Analysis Samples)

Regression Path	Control				Clinical			
	M	SD	Credible Interval		M	SD	Credible Interval	
			95% LL	95% UL			95% LL	95% UL
LRO ← RM1	.45	0.15	0.05	0.65	.54	0.12	0.29	0.76
LAUD ← CING	.38	0.13	0.11	0.65	.18	0.18	−0.16	0.54
RAUD ← CING	.22	0.19	−0.19	0.60	.41	0.15	0.10	0.70
RRO ← LM1	.22	0.38	−0.56	0.98	.54	0.09	0.34	0.72
LM1 ← SMA	.13	0.11	−0.09	0.35	.36	0.17	0.02	0.69
RM1 ← SMA	.39	0.15	0.08	0.71	.53	0.15	0.22	0.84
LAUD ← RRO	.62	0.18	0.25	1.00	.30	0.12	0.06	0.54
RM1 ← LAUD	.41	0.22	−0.06	0.82	.14	0.14	−0.13	0.42

Note. Mean is an estimate obtained by averaging across the random samples produced by the Markov chain Monte Carlo procedure. SD is analogous to the standard deviation in maximum likelihood estimation. LL = lower limit; UL = upper limit; LRO = left rolandic operculum; RM1 = right primary motor cortex; LAUD = left auditory cortex; CING = cingulate cortex; RAUD = right auditory cortex; RRO = right rolandic operculum; LM1 = left primary motor cortex; SMA = supplementary motor area.

credible intervals for the standardized regression weights estimated for the baseline population model.

Monte Carlo Study

MCMC-based simulation provides an empirical basis that allows researchers to observe the behavior of a given statistic or statistics across a particular number of random samples. A particular strength of conducting an MCMC simulation in this study is that we can examine specific methodological questions that otherwise would be either impossible or restrictively expensive to answer. Our simulation investigation focused on examining the impact of sample size on the accuracy (i.e., parameter estimation bias) and statistical power of the model to recover the baseline parameter estimates for the control and clinical groups. Accordingly, we proceeded by generating data for the variables in our model using a multivariate normal distribution for each of the following six sample sizes for both clinical and control groups: (a) $N = 10$, (b) $N = 15$, (c) $N = 20$, (d) $N = 25$, (e) $N = 50$, and (f) $N = 100$. This 6 (sample size) \times 2 (group) design resulted in 12,000 data sets each of size 1,000. For all simulations, the internal Monte Carlo facility within *Mplus* version 4.2 was used to derive maximum likelihood parameter estimates with robust standard errors (i.e., the MLR option; Muthén & Muthén, 2005, p. 268). Parameter estimates derived from the baseline model for each respective study group then served as the population starting values.

RESULTS

Table 3 provides a summary of the fit statistics obtained from the 1,000 MCMC simulations across each level of sample size by control and clinical groups. At a sample size of $N = 10$, for both groups, the chi-square was rejected at the $\alpha = .001$ level, indicating that the model did not display acceptable fit to the data. Across sample size levels of $N = 15$ and greater, for both groups the chi-square was not rejected at the $\alpha = .05$ level, indicating an acceptable level of overall fit of the model to the data. Furthermore, at sample sizes of $N = 25$ and larger, both groups displayed acceptable root mean squared error of approximation (RMSEA) point estimates (.08 or less) as recommended by Steiger (1990); however, examination of the 95% confidence intervals (CIs) reveals the possibility that, in the population, RMSEA values of greater than .08 can exist at samples sizes below 100.

Table 4 provides the true population parameters and the MCMC-generated average parameter estimates across replications by each level of sample size for the control and clinical groups. At a sample size of $N = 10$, for the normal group, three out of eight path loadings displayed parameter estimation bias of greater than 5%, and one out eight paths displayed an estimation bias greater than 10%. Specifically, in the normal group, a pattern of estimation bias greater than 5% was observed for the CING to RAUD, SMA to LM1, and SMA to RM1 paths at a sample size of $N = 10$. In the clinical group, $N = 10$ sample size, one out of eight paths (i.e., CING to LAUD) displayed parameter estimation bias greater than 5%. Across sample sizes of $N = 15$ or greater for both groups, no more than two parameter estimates presented a level of bias greater than 3%. Specifically, in the clinical group, a pattern of estimation bias greater than 3% was observed for the CING to LAUD path at a sample size of 25 or smaller.

TABLE 3
Monte Carlo Fit Statistics Summary

Sample Size	χ^2	df	p	AIC	BIC	RMSEA	RMSEA 95% CI
Control group							
10 ^a	43.54	18	< .001	1,021.59	1,027.94	0.35	0.0–.52
15	28.92	18	.05	1,622.49	1,537.25	0.17	0.0–.37
20	25.07	18	.12	2,158.73	2,114.90	0.12	0.0–.28
25	22.75	18	.20	2,695.33	2,655.81	0.08	0.0–.22
50	20.04	18	.33	5,378.90	5,353.14	0.04	0.0–.13
100	19.08	18	.38	10,748.41	10,736.79	0.03	0.0–.08
Clinical group							
10 ^a	44.68	18	< .001	1,022.67	1,029.02	0.36	0.0–.52
15	28.25	18	.06	1,529.70	1,480.46	0.17	0.0–.34
20	25.07	18	.12	2,038.86	1,995.03	0.12	0.0–.28
25	23.09	18	.18	2,543.73	2,504.21	0.08	0.0–.23
50	20.25	18	.32	5,076.53	5,050.77	0.04	0.0–.13
100	18.47	18	.42	10,139.80	10,128.19	0.02	0.0–.08

Note. AIC = Akaike Information Criterion; BIC = Bayes Information Criterion; RMSEA = root mean squared error of approximation.

^aIndicates that the fit of the model was rejected at a sample size of $N = 10$ across 1,000 replication trials.

Alternatively, in the control group, a pattern of estimation bias greater than 3% was observed for the LM1 to RRO path at all sample size conditions.

Table 5 provides the average standard errors across 1,000 replications, estimates of statistical power, and the 95% coverage proportions obtained from the MCMC analyses by level of sample size. In Tables 3 and 4, at all control and clinical group sample sizes, parameter estimates of path loadings flagged as having a bias of greater than 3%, 5%, and 10% are displayed. Table 5 provides the standard errors of parameter estimates, statistical power, and the proportion of replications for which the 95% CI contains the true population parameter. At a sample size of $N = 25$ participants per group or less, in both groups, statistical power dropped below .80 in five out of eight paths.

Finally, the tenability of the model to detect statistical differences between the groups related to their structural regression (path) weights and structural intercepts (means) yielded positive results. Simultaneous estimation of the model with both clinical and normal participants at sample size conditions of $N = 15$ or greater provided evidence that the modeling approach was sensitive to detecting statistical differences between the clinical and normal groups of participants. Specifically, differences at $p < .001$ were observed in the structural regression weights and structural intercepts between the clinical and normal participants at a sample size of $N = 15$ participants per group and greater.

DISCUSSION AND CONCLUSIONS

The aims of this study were to develop and test a path analytic model using functional imaging data representing regions of interest within the human brain, and to evaluate the performance

TABLE 4
Parameter Estimates and Estimation Bias of Path Loadings by Sample Size

Path	Sample Size											
	10				15				20			
	Contl	Pop	Clin	Pop	Contl	Pop	Clin	Pop	Contl	Pop	Clin	Pop
LRO ← RM1	.45	.45	.56	.54	.45	.45	.54	.54	.45	.45	.54	.54
LAUD ← CING	.37	.38	.19 ^b	.18	.37	.38	.19 ^a	.18	.38	.38	.19 ^a	.18
RAUD ← CING	.24 ^b	.22	.40	.41	.22	.22	.41	.41	.22	.22	.41	.41
RRO ← LM1	.26 ^c	.22	.54	.54	.23 ^a	.22	.54	.54	.21 ^a	.22	.54	.54
LM1 ← SMA	.14 ^b	.13	.36	.36	.13	.13	.36	.36	.14 ^a	.13	.36	.36
RM1 ← SMA	.41 ^b	.39	.52	.53	.38	.39	.53	.53	.39	.39	.53	.53
LAUD ← RRO	.61	.62	.30	.30	.61	.62	.30	.30	.62	.62	.30	.30
RM1 ← LAUD	.41	.41	.14	.14	.40	.41	.14	.14	.41	.41	.14	.14

Path	Sample Size											
	25				50				100			
	Contl	Pop	Clin	Pop	Contl	Pop	Clin	Pop	Contl	Pop	Clin	Pop
LRO ← RM1	.45	.45	.55	.54	.45	.45	.55	.54	.45	.45	.54	.54
LAUD ← CING	.38	.38	.17 ^a	.18	.38	.38	.17 ^a	.18	.38	.38	.18	.18
RAUD ← CING	.21 ^a	.22	.41	.41	.21 ^a	.22	.41	.41	.21 ^a	.22	.41	.41
RRO ← LM1	.21 ^a	.22	.54	.54	.23 ^a	.22	.54	.54	.23 ^a	.22	.54	.54
LM1 ← SMA	.14	.13	.36	.36	.13	.13	.36	.36	.13	.13	.36	.36
RM1 ← SMA	.39	.39	.53	.53	.39	.39	.53	.53	.39	.39	.53	.53
LAUD ← RRO	.62	.62	.30	.30	.62	.62	.30	.30	.62	.62	.30	.30
RM1 ← LAUD	.41	.41	.14	.14	.40	.41	.15	.14	.40	.41	.14	.14

Note. Contl = control group Monte Carlo estimates; Clin = clinical group Monte Carlo estimates; Pop = population parameters; LRO = left rolandic operculum; RM1 = right primary motor cortex; LAUD = left auditory cortex; CING = cingulate cortex; RAUD = right auditory cortex; RRO = right rolandic operculum; LM1 = left primary motor cortex; SMA = supplementary motor area. ^aBias greater than 3%. ^bBias greater than 5%. ^cBias greater than 10%.

of the model (i.e., parameter estimates, standard errors, and statistical power) across different sample size conditions. Using ALE and Bayesian SEM, we developed a baseline model that exhibited excellent fit to the empirical data in both the normal and clinical groups. Using our baseline model, we then evaluated the performance of the model in both groups using a Monte Carlo simulation study. Specifically, we examined the impact of sample size on the performance of the model to recover baseline model parameter estimates with an acceptable level of statistical power (.80 or greater) and with a minimal level (< 3%) of parameter estimation bias.

At a sample size of $N = 10$, in the normal group, three of eight path loadings displayed biased parameter estimates at a level greater than 5%, and one of the eight paths displayed a parameter estimation bias of greater than 10%. In the clinical group, at a sample size of $N = 10$, one of the eight path loadings displayed a parameter estimation bias of greater

TABLE 5
Standard Errors and Statistical Power for Parameter Estimates of Path Loadings by Sample Size

Path	Sample Size																	
	10			15			20			50			100					
	Contl	I - β	95% CI	Clin	I - β	95% CI	Contl	I - β	95% CI	Clin	I - β	95% CI	Contl	I - β	95% CI	Clin	I - β	95% CI
LRO ← RMI	.15	.76	.81	.25	.60	.81	.13	.85	.86	.21	.67	.87	.11	.95	.91	.19	.78	.90
LAUD ← CING	.14	.70	.80	.38	.22	.80	.16	.82	.92	.32	.16	.89	.14	.92	.90	.19	.38	.92
RAUD ← CING	.20	.34	.80	.31	.35	.80	.17	.31	.90	.26	.38	.88	.15	.34	.90	.23	.47	.88
RRO ← LMI	.46	.15	.88	.27	.65	.87	.37	.13	.91	.18	.80	.91	.33	.13	.92	.16	.88	.92
LMI ← SMA	.14	.24	.87	.39	.21	.88	.11	.26	.92	.32	.25	.92	.09	.33	.92	.27	.29	.92
RMI ← SMA	.16	.68	.84	.34	.40	.82	.13	.75	.90	.28	.50	.90	.12	.88	.91	.24	.56	.91
LAUD ← RRO	.19	.79	.82	.26	.30	.84	.16	.92	.90	.21	.34	.89	.14	.97	.90	.19	.38	.92
RMI ← LAUD	.22	.49	.84	.30	.19	.83	.18	.57	.90	.25	.15	.88	.16	.69	.90	.21	.14	.91

Path	Sample Size																	
	25			50			100											
	Contl	I - β	95% CI	Clin	I - β	95% CI	Contl	I - β	95% CI	Clin	I - β	95% CI						
LRO ← RMI	.10	.96	.91	.16	.88	.91	.07	1.00	.93	.12	.98	.94	.05	1.00	.94	.08	1.00	.95
LAUD ← CING	.12	.13	.91	.17	.42	.91	.06	1.00	.95	.18	.19	.94	.06	1.00	.94	.08	0.91	.94
RAUD ← CING	.14	.92	.92	.21	.50	.92	.10	0.56	.94	.15	.75	.94	.07	0.86	.94	.10	0.97	.94
RRO ← LMI	.29	.74	.92	.14	.94	.92	.21	0.23	.93	.10	1.00	.94	.14	0.32	.94	.07	1.00	.96
LMI ← SMA	.08	.35	.92	.25	.33	.92	.06	0.58	.96	.17	.53	.94	.04	0.85	.94	.12	0.80	.94
RMI ← SMA	.10	.91	.90	.22	.66	.90	.07	1.00	.94	.15	.91	.94	.05	1.00	.94	.11	1.00	.94
LAUD ← RRO	.12	.99	.91	.17	.42	.91	.09	1.00	.95	.12	.68	.94	.06	1.00	.94	.08	0.91	.94
RMI ← LAUD	.15	.74	.90	.20	.14	.90	.10	0.95	.95	.14	.19	.93	.07	1.00	.93	.10	0.29	.95

Note. Contl = control group Monte Carlo estimates; Clin = clinical group Monte Carlo estimates; I - β = power of statistical power to recover population parameters; 95% CI = proportion of replications for which the 95% confidence interval contains the true population parameter value; LRO = left rolandic operculum; RMI = right primary motor cortex; LAUD = left auditory cortex; CING = cingulate cortex; RAUD = right auditory cortex; RRO = right rolandic operculum; LMI = left primary motor cortex; SMA = supplementary motor area.

than 5%. This information is particularly important to the neuroscience community involved in functional imaging research in which the cost of data acquisition and analysis is high (e.g., approximately \$3,000 per participant) and participant sample sizes are often below $N = 20$. At a sample size of $N = 15$, for both normal and clinical groups, only one out of eight path loadings displayed a bias in parameter estimation greater than 3%. Furthermore, in the $N = 15$ sample size condition, the proportion of replication trials for which the 95% CI contained the true population parameters and associated standard errors ranged from 86% to 96% (i.e., 860–960 replication samples). Importantly, statistical power was observed as being below .80 (i.e., between .15 and .79) in all eight estimated regression weights (representing paths) for both groups in the sample size ($N = 10$) condition. Statistical power was observed as being below .80 in five out of the eight estimated paths for the control group and seven out of eight for the clinical group in the sample size ($N = 15$) condition. Statistical differences ($p < .001$) were observed in ROI neural activity in the network and within the ROIs for the structural regression weights and structural intercepts between the clinical and normal participants at sample size conditions of $N = 15$ participants per group and greater.

We have presented a two-step analytic approach for modeling effective connectivity among anatomic regions within the human brain using data acquired using PET. Importantly, the results of methodological-oriented neuroimaging analytic studies such as ours are of interest to the neuroscience community, in which the ongoing conduct of imaging research is crucial to an increased theoretical and applied understanding of neural systems, yet the cost of conducting such work is very high. The aims of our study were (a) to provide researchers with a highly informed approach to model the human neural system that uses ALE meta-analysis and Bayesian SEM, and (b) to evaluate the derived model regarding the impact of different sample size conditions on statistical power and parameter estimation bias. Importantly, the results from this research will aid researchers in developing informative models and most important, for planning appropriately for adequate sample sizes to ensure reliable and valid results. Our findings illustrate that the ALE/SEM-based approach performed well at sample sizes as small as $N = 15$ for both speech-impaired and normal participants. Below a sample size of $N = 15$, statistical power dropped substantially below .80 in seven out of eight regression weights (i.e., statistical power ranged from a low of .15 to a high value of .79 at a sample size of $N = 10$ in both groups), and parameter estimation bias increased above 5% in seven out of eight paths, and above 10% in 1 out of 10 paths in the clinical group. Based on these findings, we do not recommend using sample sizes less than 15 participants per analytic group. Although the primary aims of our study did not include examining the sensitivity of the model to detect statistical differences between the normal and clinical groups, we believe that the ability of the modeling approach to detect statistical differences in structural regression weights and intercepts between these groups provides a potentially powerful analytic tool to aid researchers in their work.

In summary, the two-step approach of using ALE meta-analysis and Bayesian SEM to develop a path model for investigating the effective connectivity of neural systems in humans appears to be a viable strategy at sample sizes as small as $N = 15$ participants per group. Ultimately, we believe that the results of our work will aid neuroscientists and cognitive researchers in designing SEM-based studies to evaluate and test complex network models using dynamic neuroimaging data.

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